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Assignment I: MTH 512

47
50

* Question 1.

i) The smallest n so that $Q_1, Q_2, Q_3 \in \mathbb{R}^n$ is 4

since if we take $n=3$ and $Q_1 = (1, 0, 0)$
 $Q_2 = (0, 1, 0)$
 $Q_3 = (0, 0, 1)$ $\in \mathbb{R}^3$

then $\text{span}\{Q_1, Q_2, Q_3\} = \mathbb{R}^3$ (contradiction).

ii) To prove that $Q_1+Q_2, Q_1+Q_3, Q_2+Q_3$ are independent in \mathbb{R}^n
we need to prove that the only solution of:

$$a(Q_1+Q_2) + b(Q_1+Q_3) + c(Q_2+Q_3) = 0 \text{ is } a=b=c=0$$

$$\text{so } aQ_1 + aQ_2 + bQ_1 + bQ_3 + cQ_2 + cQ_3 = 0$$

$$\Rightarrow (a+b)Q_1 + (a+c)Q_2 + (b+c)Q_3 = 0$$

since Q_1, Q_2 and Q_3 are independent in \mathbb{R}^n then

$$a+b=0, \quad a+c=0, \quad \text{and} \quad b+c=0$$

$$\Rightarrow \begin{cases} b=-a \\ c=-a \end{cases} \quad -a-a=0 \Rightarrow -2a=0 \Rightarrow a=b=c=0$$

thus $(Q_1+Q_2), (Q_1+Q_3), (Q_2+Q_3)$ are independent in \mathbb{R}^n

iii) we know that q_1, q_2 and q_3 are orthogonal

$$\text{and } Q = a_1 q_1 + a_2 q_2 + a_3 q_3$$

$$\begin{aligned} \text{for } a_1: Q \cdot q_1 &= a_1 q_1 q_1 + a_2 q_2 q_1 + a_3 q_3 q_1 \\ \Rightarrow Q \cdot q_1 &= a_1 \|q_1\|^2 + 0 + 0 \quad (\text{because they are orthogonal}) \\ \Rightarrow a_1 &= \frac{Q \cdot q_1}{\|q_1\|^2} \end{aligned}$$

$$\begin{aligned} \text{for } a_2: Q \cdot q_2 &= a_1 q_1 q_2 + a_2 q_2 q_2 + a_3 q_3 q_2 \\ Q \cdot q_2 &= 0 + a_2 \|q_2\|^2 + 0 \\ \Rightarrow a_2 &= \frac{Q \cdot q_2}{\|q_2\|^2} \end{aligned}$$

$$\begin{aligned} \text{for } a_3: Q \cdot q_3 &= a_1 q_1 q_3 + a_2 q_2 q_3 + a_3 q_3 q_3 \\ Q \cdot q_3 &= 0 + 0 + a_3 \|q_3\|^2 \\ \Rightarrow a_3 &= \frac{Q \cdot q_3}{\|q_3\|^2} \end{aligned}$$

✓/✓

* Question 2: $D = \text{span} \{(2a+3, -b+1, 6a-2b+11, 0) \mid a, b \in \mathbb{R}\}$

$$\begin{aligned} \text{i) } D &= \{(2a+3, -b+1, 6a+9-2b+2, 0) \mid a, b \in \mathbb{R}\} \\ &= \{(2a+3)(1, 0, 3, 0) + (-b+1)(0, 1, 2, 0) \mid a, b \in \mathbb{R}\} \\ &= \text{span} \{(1, 0, 3, 0), (0, 1, 2, 0)\} \end{aligned}$$

thus D is a subspace of \mathbb{R}^4 because it can be written as
span.

ii) let $Q_1 = (1, 0, 3, 0)$ and $Q_2 = (0, 1, 2, 0)$

$\{w_1, w_2\}$ is the orthogonal basis of D where:

$$w_1 = Q_1 = (1, 0, 3, 0)$$

$$w_2 = Q_2 - \frac{Q_2 \cdot w_1}{\|w_1\|^2} w_1$$

$$= (0, 1, 2, 0) - \frac{6}{10} (1, 0, 3, 0)$$

$$= (0, 1, 2, 0) - \left(\frac{3}{5}, 0, \frac{9}{5}, 0\right)$$

$$= \left(-\frac{3}{5}, 1, \frac{1}{5}, 0\right)$$

thus $\{(1, 0, 3, 0), (-\frac{3}{5}, 1, \frac{1}{5}, 0)\}$ is the orthogonal
basis of D .

* Question 3: $A = \begin{bmatrix} 5 & 3 & 1 & 1 \\ 1 & 3 & -1 & 0 \\ 2 & -6 & 4 & 1 \\ 4 & -12 & -4 & 1 \end{bmatrix}$

To see if 6 is an eigenvalue of A , we need to show that $\{(0,0,0,0)\}$ is not the solution set of: $(6I_4 - A) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$

$$\begin{pmatrix} 1 & -3 & -1 & -1 \\ -1 & 3 & 1 & 0 \\ -2 & 6 & 2 & -1 \\ -4 & 12 & 4 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \left(\begin{array}{cccc|c} x_1 & x_2 & x_3 & x_4 & \\ 1 & -3 & -1 & -1 & 0 \\ -1 & 3 & 1 & 0 & 0 \\ -2 & 6 & 2 & -1 & 0 \\ -4 & 12 & 4 & 5 & 0 \end{array} \right) \begin{array}{l} R_1 \rightarrow R_2 \rightarrow R_2 \\ 2R_1 + R_3 \rightarrow R_3 \\ 4R_1 + R_4 \rightarrow R_4 \end{array} \left(\begin{array}{cccc|c} 1 & -3 & -1 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -3 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{array} \right)$$

$$\Rightarrow \begin{cases} x_4 = 0 \\ x_1 - 3x_2 - x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_4 = 0 \\ x_1 = 3x_2 + x_3 \end{cases} \xrightarrow{\substack{\text{take } x_2 = a \\ \text{and } x_3 = b}} \begin{cases} x_1 = 3a + b \\ x_2 = a \\ x_3 = b \\ x_4 = 0 \end{cases}$$

so the solution set = $\{(3a+b, a, b, 0) \mid a, b \in \mathbb{R}\}$
 $= \text{span} \{a(3, 1, 0, 0) + b(1, 0, 1, 0) \mid a, b \in \mathbb{R}\}$

so $E_6 = \text{span} \{(3, 1, 0, 0), (1, 0, 1, 0)\}$

thus 6 is an eigenvalue of A .

✓/✓

Question 3:

$$\text{let } Q_1 = (3, 1, 0, 0) \text{ and } Q_2 = (1, 0, 1, 0)$$

$\{w_1, w_2\}$ is the orthogonal basis for E_6 where

$$w_1 = Q_1 = (3, 1, 0, 0)$$

$$w_2 = Q_2 - \frac{Q_2 \cdot w_1}{\|w_1\|^2} w_1$$

$$= (1, 0, 1, 0) - \frac{3}{10} (3, 1, 0, 0)$$

$$= \left(\frac{1}{10}, -\frac{3}{10}, 1, 0\right)$$

thus $\left\{ (3, 1, 0, 0), \left(\frac{1}{10}, -\frac{3}{10}, 1, 0\right) \right\}$ is the orthogonal basis for E_6 .



* Question 4: Let A be $n \times n$ matrix and r a fixed real number where ~~all~~ the sum of all numbers of each row of A is equal to r .

Now consider the non-zero point $Q = (1, 1, \dots, 1) \in \mathbb{R}^n$
(all entries of Q is 1)

$$A Q^T = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix} = \begin{pmatrix} a_{11} + a_{12} + \dots + a_{1n} \\ a_{21} + a_{22} + \dots + a_{2n} \\ \vdots \\ a_{n1} + a_{n2} + \dots + a_{nn} \end{pmatrix} = \begin{pmatrix} r \\ r \\ \vdots \\ r \end{pmatrix}$$

$(n \times n)$ $(n \times 1)$ $(n \times 1)$ $(n \times 1)$

$$\text{and } r Q^T = r \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix} = \begin{pmatrix} r \\ r \\ \vdots \\ r \end{pmatrix}$$

$$\text{thus } A Q^T = r Q^T$$

So r is an eigen value of A because there exists a non-zero point in \mathbb{R}^n , Q , such that $A Q^T = r Q^T$

* Question 5: $F = \begin{bmatrix} 0 & 0 & 4 & 6 \\ 1 & 3 & -1 & 0 \\ 0 & -6 & 4 & 1 \\ 4 & 12 & -4 & 2 \end{bmatrix}$

$$|F| = (-1)^{1+3} \cdot 4 \begin{vmatrix} 1 & 3 & 0 \\ 0 & -6 & 1 \\ 4 & 12 & 2 \end{vmatrix} + (-1)^{1+4} \cdot 6 \begin{vmatrix} 1 & 3 & -1 \\ 0 & -6 & 4 \\ 4 & 12 & -4 \end{vmatrix}$$

$$= 4 \left[(-1)^{4+1} \cdot 1 \begin{vmatrix} -6 & 1 \\ 12 & 2 \end{vmatrix} + (-1)^{4+2} \cdot 3 \begin{vmatrix} 0 & 1 \\ 4 & 2 \end{vmatrix} \right] - 6 \left[(-1)^{4+1} \cdot 1 \begin{vmatrix} -6 & 4 \\ 12 & -4 \end{vmatrix} + (-1)^{3+1} \cdot 4 \begin{vmatrix} 3 & -1 \\ -6 & 4 \end{vmatrix} \right]$$

$$= 4 [(-12 - 12) - 3(-4)] - 6 [(24 - 48) + 4(12 - 6)]$$

$$= 4(-24 + 12) - 6(-24 + 24)$$

$$= -48$$

so $|F| = -48$

D $\xrightarrow{-2R_2}$ F thus $|F| = -2|D| \Rightarrow |D| = -\frac{1}{2}|F| = 24$

C $\xrightarrow{R_3 \leftrightarrow R_2}$ D thus $|D| = -|C| \Rightarrow |C| = -24$

B $\xrightarrow{-6R_1, R_4 \rightarrow R_4}$ C thus $|C| = |B| \Rightarrow |B| = -24$ ✓

A $\xrightarrow{3R_2}$ B thus $|B| = 3|A| \Rightarrow |A| = \frac{1}{3}|B| = -8$

W/W

* Question 6:

$$i) L = \{(a, b^3, 0) \mid a, b \in \mathbb{R}\}$$

• axiom 1: let $Q_1, Q_2 \in L$ then $Q_1 = \alpha_1 a + \alpha_2 b^3 + 0$ for some const α_1, α_2
 $Q_2 = \beta_1 a + \beta_2 b^3 + 0$ for some const β_1, β_2

$$\text{thus } Q_1 + Q_2 = (\alpha_1 + \beta_1)a + (\alpha_2 + \beta_2)b^3 + 0$$

$$\text{so } Q_1 + Q_2 \in L$$

• axiom 2: let $Q \in L$ and α be a constant

$$\text{then } Q = \alpha_1 a + \alpha_2 b^3 + 0$$

$$\text{and } \alpha Q = (\alpha \alpha_1)a + (\alpha \alpha_2)b^3 + 0$$

$$\text{so } \alpha Q \in L$$

• axiom 3: take $a=b=0$ thus $(0, 0, 0) \in L$

So L is a subspace of \mathbb{R}^3 .

$$(ii) L = \{(a, 0, b^2) \mid a, b \in \mathbb{R}\}$$

Take $Q = (0, 0, 4) \in L$ where $a=0$ and $b=2$

and consider $\alpha = -1$

$$\text{thus } \alpha Q = (0, 0, -4) \notin L$$

thus L is not a subspace of \mathbb{R}^3 since axiom 2 fails.

NO $\rightarrow \mathbb{R}$

$\in \mathbb{R}$
not a point

X

0/3

m/m

* Question 6:

iii) $L = \{ (b, b^3, 0) \mid b \in \mathbb{R} \}$

Take $Q = (1, 1, 0) \in L$ such that $b=1$

and consider $\alpha=2$

then $\alpha Q = (2, 2, 0) \notin L$

thus L is not a subspace of \mathbb{R}^3

M/M

iv) let us find the solution set of $(3I_4 - A)X = 0$

$$\begin{pmatrix} 3 & 0 & 0 & 0 \\ -1 & 3 & 0 & 0 \\ 0 & -1 & 3 & -4 \\ 0 & 0 & -1 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 3 & 0 & 0 & 0 & | & 0 \\ -1 & 3 & 0 & 0 & | & 0 \\ 0 & -1 & 3 & -4 & | & 0 \\ 0 & 0 & -1 & 3 & | & 0 \end{pmatrix} \xrightarrow[\frac{1}{3}R_1]{\frac{1}{3}R_2} \begin{pmatrix} 1 & 0 & 0 & 0 & | & 0 \\ -1 & 3 & 0 & 0 & | & 0 \\ 0 & -1 & 3 & -4 & | & 0 \\ 0 & 0 & -1 & 3 & | & 0 \end{pmatrix}$$

$\downarrow R_1 + R_2 \rightarrow R_2$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & | & 0 \\ 0 & 1 & 0 & 0 & | & 0 \\ 0 & -1 & 3 & -4 & | & 0 \\ 0 & 0 & -1 & 3 & | & 0 \end{pmatrix} \xrightarrow[\frac{1}{3}R_2]{\frac{1}{3}R_3} \begin{pmatrix} 1 & 0 & 0 & 0 & | & 0 \\ 0 & 3 & 0 & 0 & | & 0 \\ 0 & -1 & 3 & -4 & | & 0 \\ 0 & 0 & -1 & 3 & | & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & | & 0 \\ 0 & 1 & 0 & 0 & | & 0 \\ 0 & 0 & 3 & -4 & | & 0 \\ 0 & 0 & -1 & 3 & | & 0 \end{pmatrix} \xrightarrow{\frac{1}{3}R_3} \begin{pmatrix} 1 & 0 & 0 & 0 & | & 0 \\ 0 & 1 & 0 & 0 & | & 0 \\ 0 & 0 & 1 & -\frac{4}{3} & | & 0 \\ 0 & 0 & -1 & 3 & | & 0 \end{pmatrix}$$

$$\xrightarrow{R_3+R_4 \rightarrow R_4} \left(\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -\frac{4}{3} & 0 \\ 0 & 0 & 0 & \frac{5}{3} & 0 \end{array} \right)$$

η/η

$$\xrightarrow{\frac{3}{5}R_4} \left(\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -\frac{4}{3} & 0 \\ 0 & 0 & 0 & 1 & 0 \end{array} \right) \xrightarrow{\frac{4}{3}R_4 + R_3 \rightarrow R_3} \left(\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{array} \right)$$

thus solution set of $(3I_4 - A)X = 0$ is $\{(0, 0, 0, 0)\}$
 therefore 3 is not an eigenvalue of A.

v) let A be a 4×4 matrix where $A_2 = A_4$ (columns)

$$\text{solve the system } A \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = A_2$$

$$\Rightarrow A_2 = x_1 A_1 + x_2 A_2 + x_3 A_3 + x_4 A_4$$

$$A_2 = x_1 A_1 + (x_2 + x_4) A_2 + x_3 A_3$$

$$\text{thus } \begin{cases} x_1 = 0 \\ x_2 + x_4 = 1 \\ x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = 0 \\ x_2 = 1 - x_4 \\ x_3 = 0 \end{cases} \xrightarrow{\text{take } x_4 = a} \begin{cases} x_1 = 0 \\ x_2 = 1 - a \\ x_3 = 0 \\ x_4 = a \end{cases}$$

thus the solution set of $AX = A_2 = \{(0, 1-a, 0, a) \mid a \in \mathbb{R}\}$

so it has infinitely many solutions ~~for~~

and $(0, 0, 0, 1)$, $(0, -1, 0, 2)$, $(0, -2, 0, 3)$ are
(a=1) (a=2) (a=3)

3 distinct points that belong to the solution set of the system.